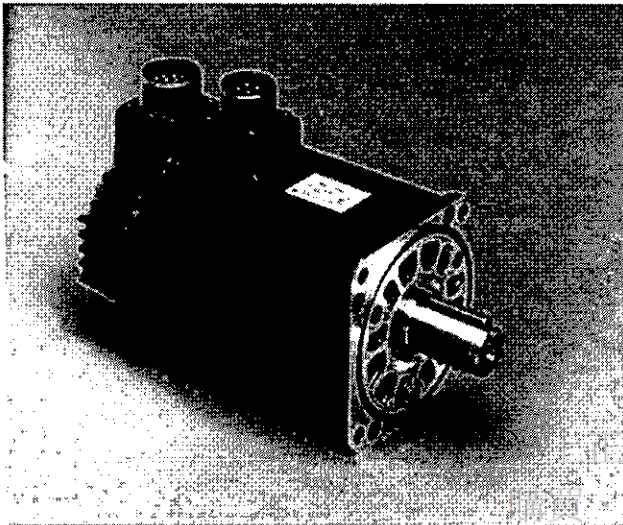


## Super High Power Rate Series

# SGMS Servomotors (3000rpm) - With Incremental / Absolute Encoder

Rated Output: 1.0kW, 1.5kW, 2.0kW,  
3.0kW, 4.0kW, 5.0kW



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SGMS Dimensions	112 - 115
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SGMS Optional CE Selection	121 - 125
SGDB Ratings & Specifications	129 - 130
SGDB Dimensions	131 - 137

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維修 此手冊零組件

## Design Features

### 1. Compact

- Small sized motor

Six frame sizes: up to 140 in. lb. RMS - torque.

### 2. High Speed

- Rated Speed: 3000 RPM
- Maximum Speed: 4500 RPM

### 3. Encoders

- 4095 PPR incremental encoder standard
- 8192 PPR absolute encoder (option)

### 4. Enclosure

- Totally enclosed, self-cooled IP67 (excluding shaft)
- IP67 with shaft seal (option)

### 5. Application Emphasis

- High torque-to inertia ratio
- Chip mounters
- PCB drilling machines
- Robots
- Conveyors
- Packaging

### 6. Certified International Standards

- UL Recognized and c-UL pending (File # E165827), CE compliance (option)

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Line id: @zzzz

[www.repairtw.com](http://www.repairtw.com)

# Servomotor Ratings and Specifications

Time Rating: Continuous  
 Insulation: Class F  
 Vibration: 15µm or less  
 Withstand Voltage: 1500VAC  
 Insulation Resistance: 500VDC  
 10MΩ min.

Enclosure: Totally-enclosed, self-cooled  
 IP67 (except for shaft opening)  
 Ambient Temperature: 0 to 40°C  
 Ambient Humidity: 20 to 80%  
 (non-condensing)  
 Rated Speed: 3000 rpm  
 Instantaneous Max Speed: 4500 rpm

Excitation: Permanent magnet  
 Drive Method: Direct drive  
 Mounting: Flange-mounted  
 Painting Color: Muncell notation  
 N1.5

MOTORS: SGMS-	Rated Output*	Rated Torque*		Instantaneous Peak Torque*		Rated Current*	Instantaneous Max Current*
	kW (HP)	N·m	kgf·cm (lb·in)	N·m	kgf·cm (lb·in)	A (rms)	A (rms)
10A□A	1.0 (1.3)	3.18	32.4 (28.2)	9.54	97.2 (84.4)	5.7	17
15A□A	1.5 (2.0)	4.9	50 (43)	14.7	150 (130)	9.5	28
20A□A	2.0 (2.7)	6.36	65 (56.4)	19.1	195 (169)	12.4	42
30A□A	3.0 (4.0)	9.8	100 (87)	29.4	300 (260)	18.8	56
40A□A	4.0 (5.4)	12.6	129 (112)	37.8	387 (336)	24.3	77
50A□A	5.0 (6.7)	15.8	161 (140)	47.6	486 (422)	28.2	84

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MOTORS: SGMS-	Torque Constant		Moment of Inertia		Holding Brake Torque	Holding Brake Inertia		Allowable Load Inertia	Rated Power Rate*	Rated Angular Acceleration*	Inertia Time Constant	Inductive Time Constant
	N·m/A (rms)	kgf·cm/A (lb·in/A) (rms)	kg·m <sup>2</sup> × 10 <sup>-4</sup>	gf·cm·s <sup>2</sup> (lb·in·s <sup>2</sup> × 10 <sup>-3</sup> )		kg·m <sup>2</sup> × 10 <sup>-4</sup>	gf·cm·s <sup>2</sup> (lb·in·s <sup>2</sup> × 10 <sup>-3</sup> )					
10A□A	0.64	6.5 (5.6)	1.74	1.78 (1.54)	7.84	0.215	0.219 (0.190)	1.74	57.9	18250	0.87	7.1
15A□A	0.57	5.8 (5.1)	2.47	2.52 (2.19)				2.47	97.2	19840	0.71	7.7
20A□A	0.56	5.7 (5.0)	3.19	3.26 (2.82)				3.19	127	19970	0.58	8.3
30A□A	0.57	5.8 (5.1)	7.00	7.14 (6.20)	2.0	1.85	1.89 (1.64)	7.0	137	14000	0.74	13.0
40A□A	0.55	5.6 (4.9)	9.60	9.80 (8.50)				9.6	166	13160	0.60	14.1
50A□A	0.61	6.2 (5.4)	12.3	12.6 (10.9)				12.3	202	12780	0.57	14.7

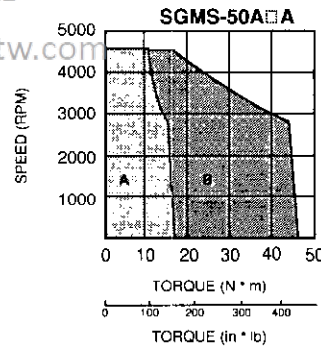
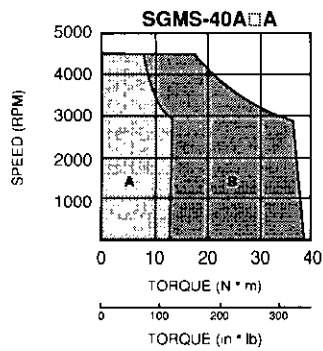
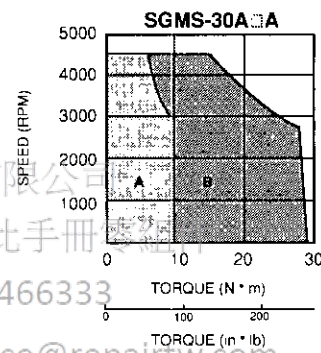
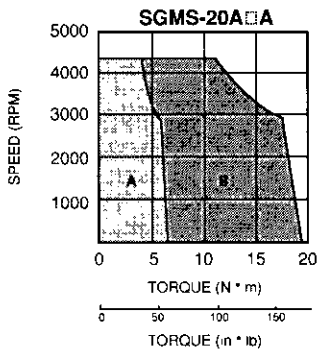
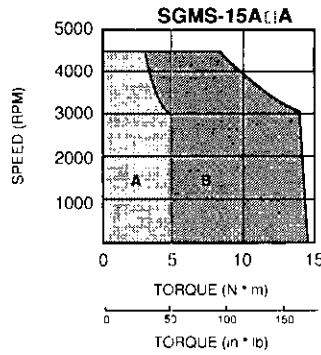
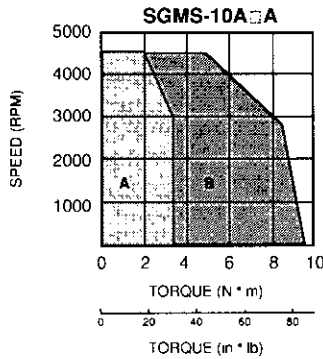
\* These items and torque-speed characteristics quoted in combination with an SGDB Servo Amplifier at an armature winding temperature of 20°C.

Note: These characteristics can be obtained when the following heat sinks (steel plates) are used for cooling purposes:

Type 10A□A to 20A□A: 300 × 300 × 12 (mm) (11.81 × 11.81 × 0.47 (in))  
 Type 30A□A to 50A□A: 400 × 400 × 20 (mm) (15.75 × 15.75 × 0.79 (in))



# Speed / Torque Curves



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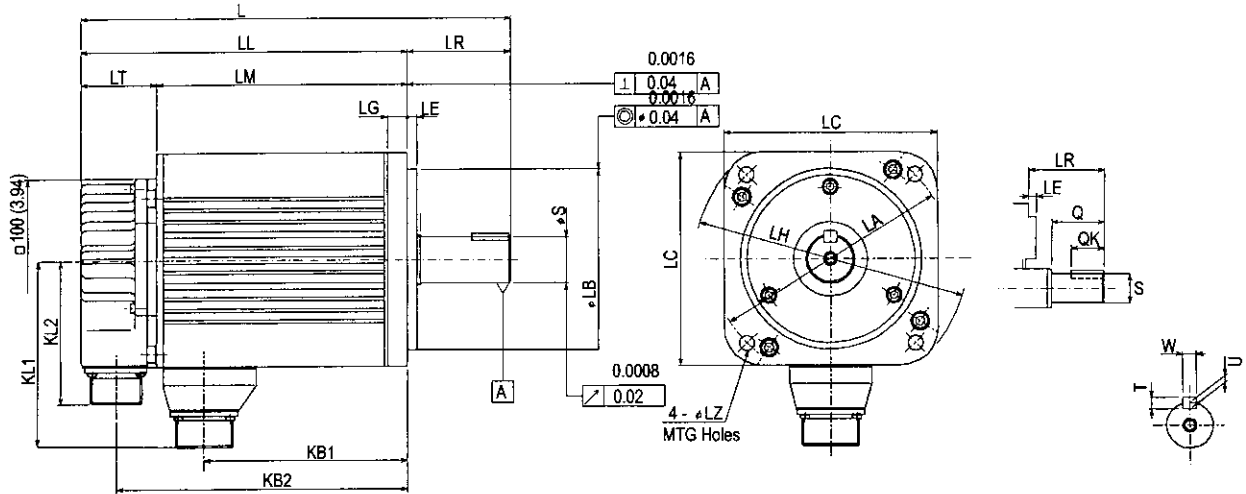


**A** : CONTINUOUS DUTY ZONE

**B** : INTERMITTENT DUTY ZONE

## Dimensions in inches (mm)

### (1) 4096 PPR Incremental Encoder



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Type SGMS	L	LL	LM	LR	LT	KB1	KB2	KL1	KL2	Flange Dimensions								Shaft End Dimension		Approx. Mass b (kg)
										LA	LB	LC	LE	LG	LH	LJ	LZ	S	Q	
10A6AB	7.64 (194)	5.87 (149)	4.06 (103)	1.77 (45)	1.81 (46)	2.99 (76)	5.04 (128)	3.78 (96)	3.43 (87)	4.53 (115)	3.74 (95) $\pm 0.035$	3.94 (100)	0.12 (3)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7)	0.94 (24) $\pm 0.013$	1.57 (40)	10.1 (4.6)
15A6AB	8.66 (220)	6.89 (175)	5.08 (129)	1.77 (45)	1.81 (46)	4.02 (102)	6.06 (154)	3.78 (96)	3.43 (87)	4.53 (115)	3.74 (95) $\pm 0.035$	3.94 (100)	0.12 (3)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7)	0.94 (24) $\pm 0.013$	1.57 (40)	12.8 (5.8)
20A6AB	9.57 (243)	7.8 (198)	5.98 (152)	1.77 (45)	1.81 (46)	4.92 (125)	6.97 (177)	3.78 (96)	3.43 (87)	4.53 (115)	3.74 (95) $\pm 0.035$	3.94 (100)	0.12 (3)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7)	0.94 (24) $\pm 0.013$	1.57 (40)	15.4 (7.0)
30A6AB	10.31 (262)	7.83 (199)	6.02 (153)	2.48 (63)	1.81 (46)	4.8 (122)	7.01 (178)	4.49 (114)	3.43 (87)	5.71 (145)	4.33 (110) $\pm 0.035$	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	1.77 (45)	0.35 (9)	1.1 (28) $\pm 0.013$	2.17 (55)	24.3 (11)
40A6AB	11.77 (299)	9.29 (236)	7.48 (190)	2.48 (63)	1.81 (46)	6.26 (159)	8.46 (215)	4.49 (114)	3.43 (87)	5.71 (145)	110 (4.33) $\pm 0.014$	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	1.77 (45)	0.35 (9)	1.1 (28) $\pm 0.013$	2.17 (55)	30.9 (14)
50A6AB	13.35 (339)	10.87 (276)	9.06 (230)	2.48 (63)	1.81 (46)	7.83 (199)	10.04 (255)	4.49 (114)	3.43 (87)	5.71 (145)	110 (4.33) $\pm 0.014$	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	1.77 (45)	0.35 (9)	1.1 (28) $\pm 0.013$	2.17 (55)	37.5 (17)

- Note:
1. Incremental Encoder (4096 PPR) is used as a detector.
  2. Dimensions are the same when using other incremental encoders.
  3. Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 "Limits and Fits for Engineering."
  4. There are no dimensional changes on the CE products.

#### Connector Specifications

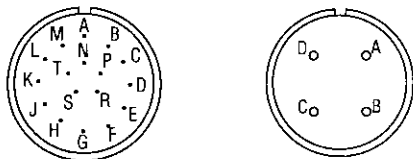
Receptacle: MS3102A20-29P

Applicable Plug: (To be prepared by customer)

Plug: MS3108B20-29S (L Type)

MS3106B20-29S (Straight Type)

Cable Clamp: MS3057-12A

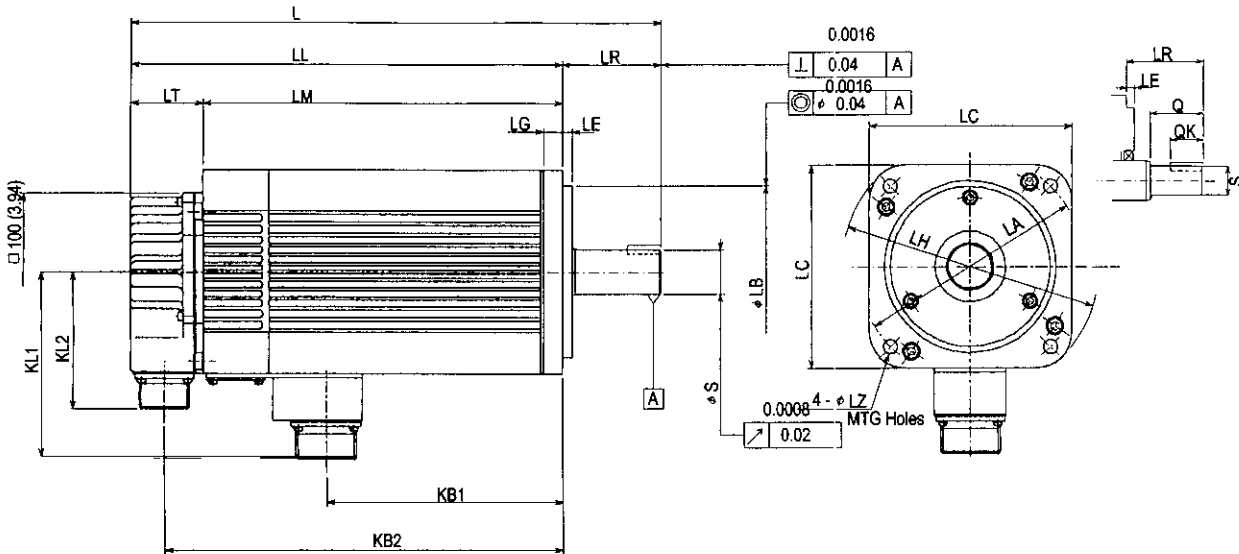


Connector Wiring on the Incremental Encoder		
A	Channel A Output	K
B	Channel A Output	L
C	Channel B Output	M
D	Channel B Output	N
E	Channel C Output	P
F	Channel C Output	R
G	0V	S
H	+5 VDC	T
J	FG (Frame Ground)	

Connector Wiring on the Motor Side	
A	U Phase
B	V Phase
C	W Phase
D	Ground Terminal

Note: The above-mentioned detector side specifications are common to all the motors with incremental encoders.

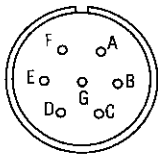
## (2) 4096 PPR Incremental Encoder, with Brake



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Type SGMS	L	LL	LM	LR	LT	KB1	KB2	KL1	KL2	Flange Dimensions							Shaft End Dimension		Approx. Mass b (kg)	
										LA	LB	LC	LE	LG	LH	LJ	LZ	S		Q
10A6ABC	9.37 (238)	7.6 (193)	5.79 (147)	1.77 (45)	1.81 (46)	2.64 (67)	6.77 (172)	3.94 (100)	3.43 (87)	4.53 (115)	3.74 (95) <sub>0.035</sub>	3.94 (100)	0.12 (3) (10)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7) (24) <sub>0.013</sub>	0.94 (24) <sub>0.013</sub>	1.57 (40)	13.2 (6.0)
15A6ABC	10.39 (264)	8.62 (219)	6.81 (173)	1.77 (45)	1.81 (46)	3.66 (93)	7.8 (198)	3.94 (100)	3.43 (87)	4.53 (115)	3.74 (95) <sub>0.035</sub>	3.94 (100)	0.12 (3) (10)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7) (24) <sub>0.013</sub>	0.94 (24) <sub>0.013</sub>	1.57 (40)	16.5 (7.5)
20A6ABC	11.3 (287)	9.53 (242)	7.72 (196)	1.77 (45)	1.81 (46)	4.57 (116)	8.7 (221)	3.94 (100)	3.43 (87)	4.53 (115)	3.74 (95) <sub>0.035</sub>	3.94 (100)	0.12 (3) (10)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7) (24) <sub>0.013</sub>	0.94 (24) <sub>0.013</sub>	1.57 (40)	18.7 (8.5)
30A6ABC	11.81 (300)	9.33 (237)	7.52 (191)	2.48 (63)	1.81 (46)	4.45 (113)	8.5 (216)	4.69 (119)	3.43 (87)	5.71 (145)	4.33 (110) <sub>0.035</sub>	5.12 (130)	0.24 (6) (12)	0.47 (12)	6.5 (165)	1.77 (45)	0.35 (9) (28) <sub>0.013</sub>	1.1 (28) <sub>0.013</sub>	2.17 (55)	30.9 (14)
40A6ABC	13.27 (337)	10.79 (274)	8.98 (228)	2.48 (63)	1.81 (46)	5.91 (150)	9.96 (253)	4.69 (119)	3.43 (87)	5.71 (145)	4.33 (110) <sub>0.035</sub>	5.12 (130)	0.24 (6) (12)	0.47 (12)	6.5 (165)	1.77 (45)	0.35 (9) (28) <sub>0.013</sub>	1.1 (28) <sub>0.013</sub>	2.17 (55)	37.5 (17)
50A6ABC	13.27 (377)	12.36 (314)	10.55 (268)	2.48 (63)	1.81 (46)	7.48 (190)	11.54 (293)	4.69 (119)	3.43 (87)	5.71 (145)	4.33 (110) <sub>0.035</sub>	5.12 (130)	0.24 (6) (12)	0.47 (12)	6.5 (165)	1.77 (45)	0.35 (9) (28) <sub>0.013</sub>	1.1 (28) <sub>0.013</sub>	2.17 (55)	44.1 (20)

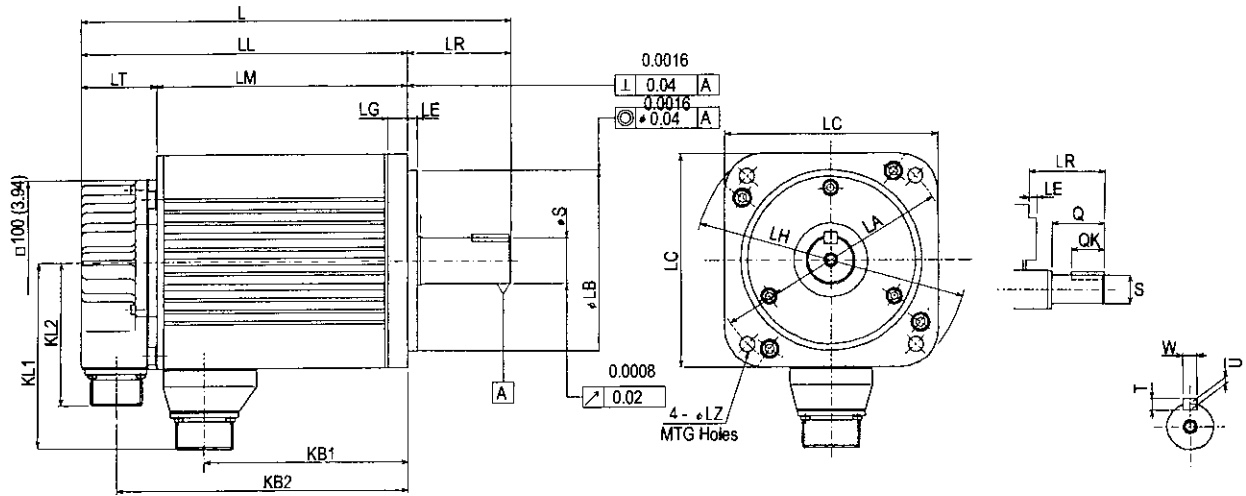
- Note:
1. Incremental Encoder (4096 PPR) is used as a detector.
  2. Dimensions are the same when using other incremental encoders.
  3. Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 "Limits and Fits for Engineering."
  4. There are no dimensional changes on the CE products.



Connector Wiring on the Motor Side			
A	U Phase	E	Brake Terminal
B	V Phase	F	Brake Terminal
C	W Phase	G	-
D	FG Frame Ground		



## (3) 8192 PPR Absolute Encoder (15 bit)



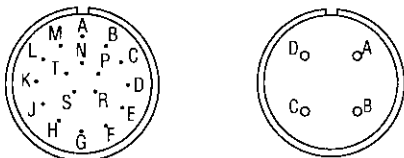
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Type SGMS-	L	LL	LM	LR	LT	KB1	KB2	KL1	KL2	Flange Dimensions							Shaft End Dimension		Approx. Mass lb (kg)	
										LA	LB	LC	LE	LG	LH	LJ	LZ	S		Q
10ASAB	8.19 (208)	6.42 (163)	4.06 (103)	1.77 (45)	2.36 (60)	2.99 (76)	5.59 (142)	3.78 (96)	3.43 (87)	4.53 (115)	3.74 (95) 0.035	3.94 (100)	0.12 (3)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7)	0.94 (24) 0.013	1.57 (40)	11 (5.0)
15ASAB	9.21 (234)	7.44 (189)	5.08 (129)	1.77 (45)	2.36 (60)	4.02 (102)	6.61 (168)	3.78 (96)	3.43 (87)	4.53 (115)	3.74 (95) 0.035	3.94 (100)	0.12 (3)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7)	0.94 (24) 0.013	1.57 (40)	13.7 (6.2)
20ASAB	10.12 (257)	8.35 (212)	5.98 (152)	1.77 (45)	2.36 (60)	4.92 (125)	7.52 (191)	3.78 (96)	3.43 (87)	4.53 (115)	3.74 (95) 0.035	3.94 (100)	0.12 (3)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7)	0.94 (24) 0.013	1.57 (40)	16.3 (7.4)
30ASAB	10.87 (276)	8.39 (213)	6.02 (153)	2.48 (63)	2.36 (60)	4.8 (122)	7.56 (192)	4.49 (114)	3.43 (87)	5.71 (145)	4.33 (110) 0.035	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	1.77 (45)	0.35 (9)	1.1 (28) 0.013	2.17 (55)	25.4 (11.5)
40ASAB	12.32 (313)	9.84 (250)	7.48 (190)	2.48 (63)	2.36 (60)	6.26 (159)	9.02 (229)	4.49 (114)	3.43 (87)	5.71 (145)	4.33 (110) 0.035	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	1.77 (45)	0.35 (9)	1.1 (28) 0.013	2.17 (55)	32 (14.5)
50ASAB	13.9 (353)	11.42 (290)	9.06 (230)	2.48 (63)	2.36 (60)	7.83 (199)	10.59 (269)	4.49 (114)	3.43 (87)	5.71 (145)	4.33 (110) 0.035	5.12 (130)	0.24 (6)	0.47 (12)	6.5 (165)	1.77 (45)	0.35 (9)	1.1 (28) 0.013	2.17 (55)	38.6 (17.5)

- Note:
1. Incremental Encoder (8192 PPR) is used as a detector.
  2. Dimensions are the same when using other incremental encoders.
  3. Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 "Limits and Fits for Engineering."
  4. There are no dimensional changes on the CE products.

### Connector Specifications

Receptacle: MS3102A20-29P  
 Applicable Plug: (To be prepared by customer)  
 Plug: MS3108B20-29S (L Type)  
 MS3106B20-29S (Straight Type)  
 Cable Clamp: MS3057-12A

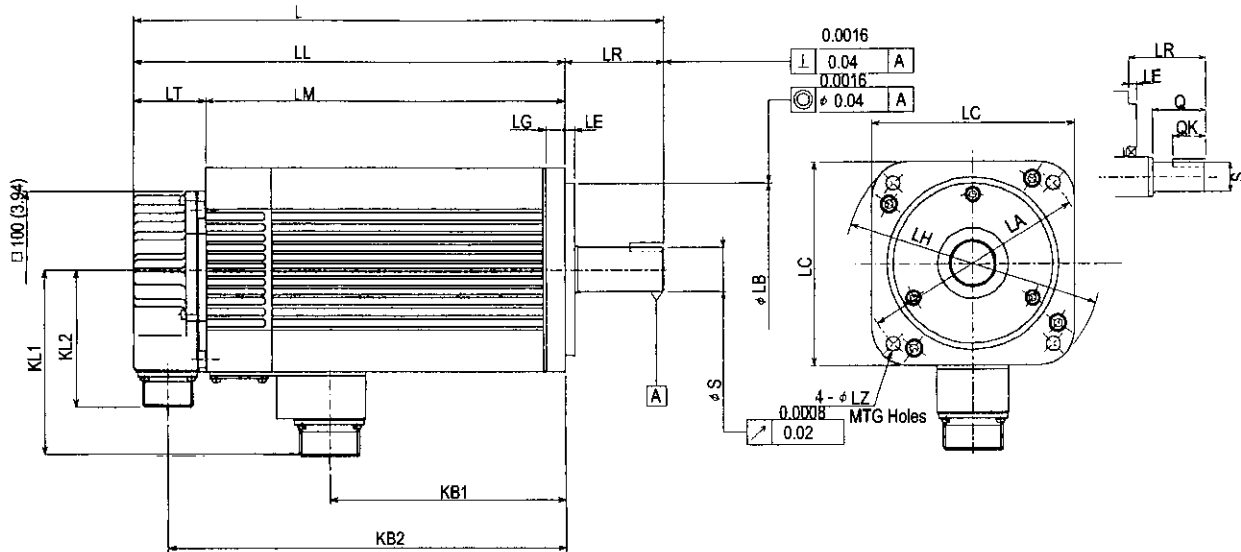


Connector Wiring on the Incremental Encoder (When using 8192 PPR (15 bits))			
A	Channel A Output	K	-
B	Channel A Output	L	-
C	Channel B Output	M	-
D	Channel B Output	N	-
E	Channel Z (C) Output	P	-
F	Channel Z (C) Output	R	Reset
G	0V	S	0V (battery)
H	+5 VDC	T	3.6V (battery)
J	FG (Frame Ground)		

Connector Wiring on the Motor Side	
A	U Phase
B	V Phase
C	W Phase
D	FG (Frame Ground)

Note: The above-mentioned detector side specifications are common to all the motors with incremental encoders.

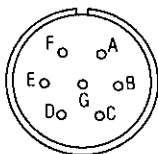
## (4) 8192 PPR Absolute Encoder (15 bit), With Brake



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Type SGMS	L	LL	LM	LR	LT	KB1	KB2	KL1	KL2	Flange Dimensions								Shaft End Dimension		Approx. Mass b (kg)
										LA	LB	LC	LE	LG	LH	LJ	LZ	S	Q	
10ASABC	9.92 (252)	8.15 (207)	5.79 (147)	1.77 (45)	2.36 (60)	2.64 (67)	7.32 (186)	3.94 (100)	3.43 (87)	4.53 (115)	3.74 (95) $\frac{0}{-0.035}$	3.94 (100)	0.12 (3)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7)	0.94 (24) $\frac{0}{-0.013}$	1.57 (40)	14.3 (65)
15ASABC	10.94 (278)	9.17 (233)	6.81 (173)	1.77 (45)	2.36 (60)	3.66 (93)	8.35 (212)	3.94 (100)	3.43 (87)	4.53 (115)	3.74 (95) $\frac{0}{-0.035}$	3.94 (100)	0.12 (3)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7)	0.94 (24) $\frac{0}{-0.013}$	1.57 (40)	17.6 (8.0)
20ASABC	11.85 (301)	10.08 (256)	7.72 (196)	1.77 (45)	2.36 (60)	4.57 (116)	9.25 (235)	3.94 (100)	3.43 (87)	4.53 (115)	3.74 (95) $\frac{0}{-0.035}$	3.94 (100)	0.12 (3)	0.39 (10)	5.12 (130)	1.77 (45)	0.28 (7)	0.94 (24) $\frac{0}{-0.013}$	1.57 (40)	19.8 (9.0)
30ASABC	12.36 (314)	9.88 (251)	7.52 (191)	2.48 (63)	2.36 (60)	4.45 (113)	9.06 (230)	4.69 (119)	3.43 (87)	5.71 (145)	4.33 (110) $\frac{0}{-0.035}$	5.12 (130)	0.24 (6)	0.47 (2)	6.5 (165)	1.77 (45)	0.35 (9)	1.1 (28) $\frac{0}{-0.013}$	2.17 (55)	32 (14.5)
40ASABC	13.82 (351)	11.34 (288)	8.98 (228)	2.48 (63)	2.36 (60)	5.91 (150)	10.51 (267)	4.69 (119)	3.43 (87)	5.71 (145)	4.33 (110) $\frac{0}{-0.035}$	5.12 (130)	0.24 (6)	0.47 (2)	6.5 (165)	1.77 (45)	0.35 (9)	1.1 (28) $\frac{0}{-0.013}$	2.17 (55)	38.6 (17.5)
50ASABC	15.39 (391)	12.91 (328)	10.55 (268)	2.48 (63)	2.36 (60)	7.48 (190)	12.09 (307)	4.69 (119)	3.43 (87)	5.71 (145)	4.33 (110) $\frac{0}{-0.035}$	5.12 (130)	0.24 (6)	0.47 (2)	6.5 (165)	1.77 (45)	0.35 (9)	1.1 (28) $\frac{0}{-0.013}$	2.17 (55)	45.2 (20.5)

- Note:
1. Incremental Encoder (8192 PPR) is used as a detector.
  2. Dimensions are the same when using other incremental encoders.
  3. Tolerances on the dimensions LB of flange type and S of shaft extensions are based on JIS (Japanese Industrial Standard) B0401 "Limits and Fits for Engineering."
  4. There are no dimensional changes on the CE products.

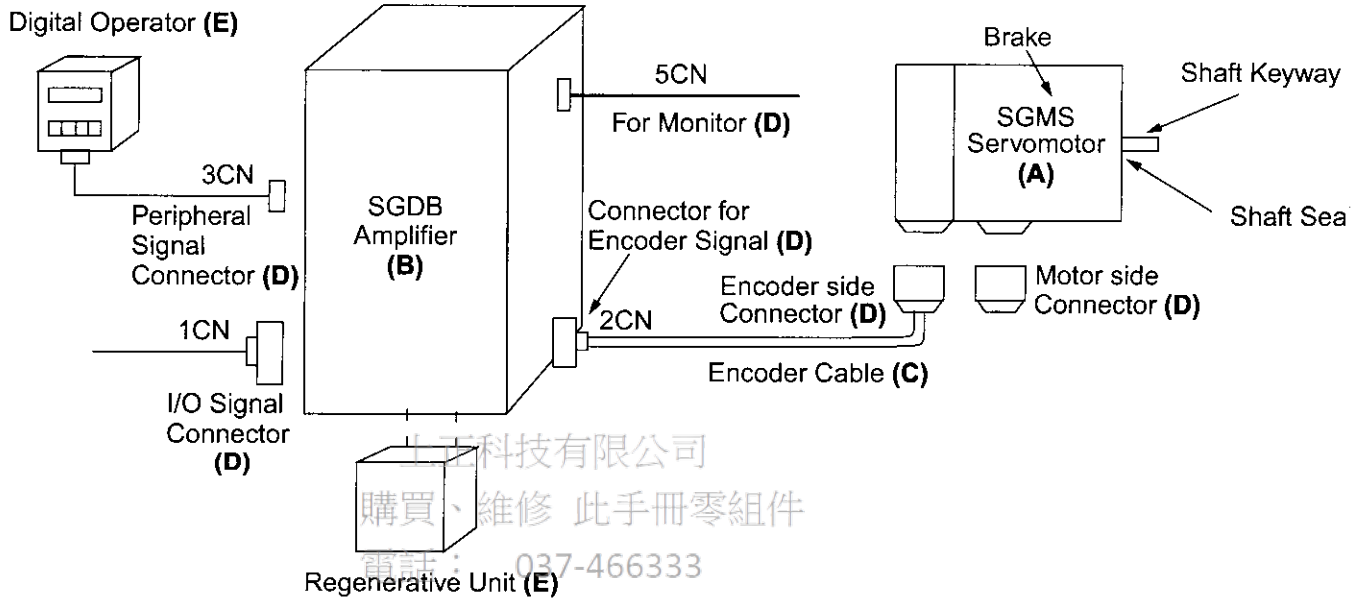


Connector Wiring on the Motor Side			
A	U Phase	E	Brake Terminal
B	V Phase	F	Brake Terminal
C	W Phase	G	-
D	FG (Frame Ground)		

# Selecting Your SGMS Sigma Servo System

Use the diagram below to locate and identify the components of your system. Each item is letter-coded and cross-referenced in the option tables on the following pages.

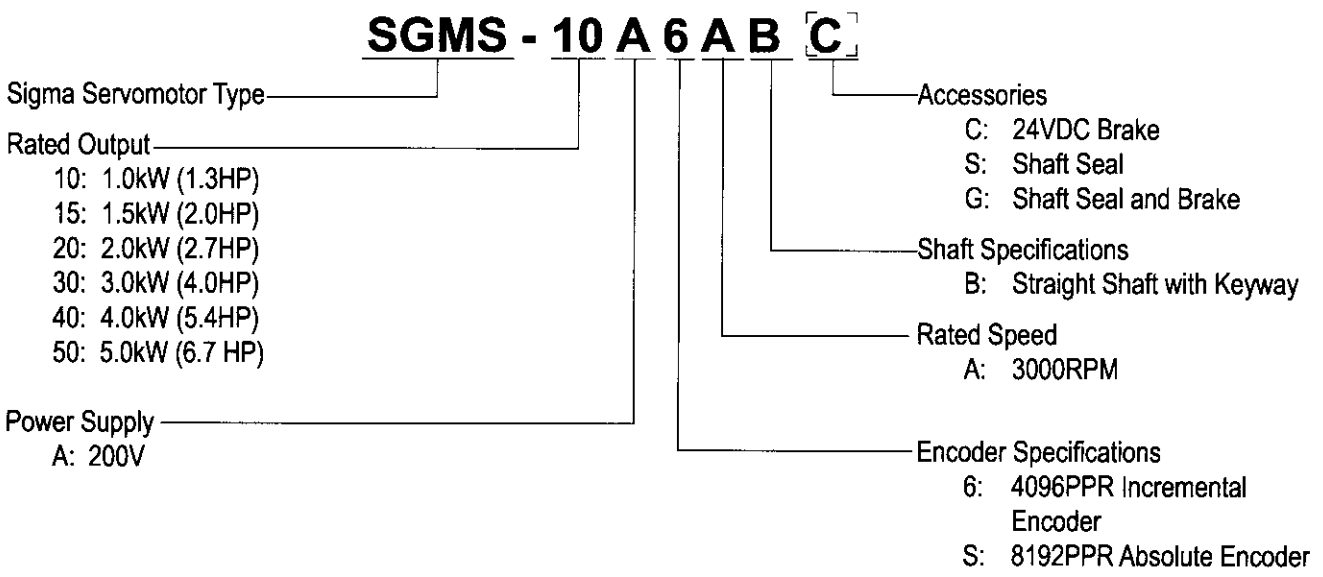
## System Configuration



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## Model Number Designation



Note: **Bold** items are Stock Products usually available from inventory. Contact your Yaskawa representative for delivery on all other items.



## Servomotor & Amplifier Selection

Use the table below to select the appropriate SGMS Sigma Servomotor and Amplifier.

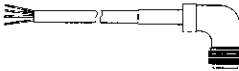
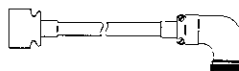
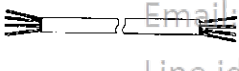
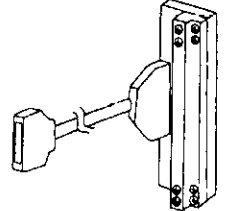
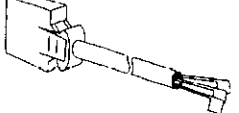
Description	Peak Torque (in. lb.)	Rated Torque (in. lb.)	Motor Inertia (in. lb. sec <sup>2</sup> x 10 <sup>-3</sup> )	Motor MODEL # (A)	Amplifier MODEL # (B)* Analog/Digital Input SGDB-	Motor & Amplifier Item Class
	84.4	28.2	1.54	SGMS-10A6AB	10ADG	Stock
				SGMS-10A6ABC		
200V 3-Phase	130	43	2.19	SGMS-15A6AB	15ADG	
				SGMS-15A6ABC		
4096 PPR Incremental Encoder	169	56.4	2.82	SGMS-20A6AB	20ADG	
				SGMS-20A6ABC		
Straight Shaft with Keyway	260	87	6.2	SGMS-30A6AB	30ADG	
				SGMS-30A6ABC		
MS Connectors	336	112	8.5	SGMS-40A6AB	44ADG	
				SGMS-40A6ABC		
	422	140	11	SGMS-50A6AB		
				SGMS-50A6ABC		

Note: 24VDC brakes for SGMS Sigma servomotors are standard. Contact a local source for 24VDC power supplies.  
For technical information, request manual number TSE-S800-16 from your Yaskawa representative.

\* For more detailed SGDB amplifier specifications and dimensions, refer to page 127.

## Pre-wired Cable Selection

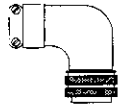
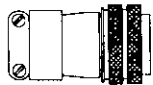


Use the table below to select Pre-wired Cables for your SGMS Sigma Servomotor.

Cable Description (C)	Motor Size (kW)	Part Number		Comments	Item Class
		without Brake	with Brake		
Power Cable with L-type Connectors 	1.0, 1.5, 2.0	B1E-□	B1BE-□	Use the following key to specify required cable length (last digit of part #): 1: 3 meters 2: 5 meters 3: 10 meters (standard) 4: 15 meters 5: 20 meters	
	3.0	B2E-□	B2BE-□		
	4.0, 5.0	B3E-□	B3BE-□		
Encoder Cable (incremental or absolute) 		DE9407237-□E			
Encoder Cable Only for Solder Connections 		DP8409123		Up to 70 feet; for use with mating connector.	
Encoder Cable Only for Solder Connections		DP8409179		Over 70 feet; splice cable to accommodate connector.	Stock *
Input/Output 1CN Cable & Transition Terminal Block 	All	JUSP-TA50P		35 mm din rail mountable; the cable length is 0.5 meters.	
Input/Output 1CN Cable with Pigtail Leads 		DE9406969-□		Use the following key to specify required cable length (last digit of part #): 1: 1 meter (standard) 2: 2 meters 3: 3 meters	

\* Standard cable lengths are Stock items; non-standard cable lengths are Limited Stock items.

## Mating Connector Selection

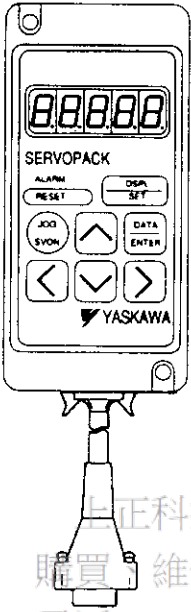
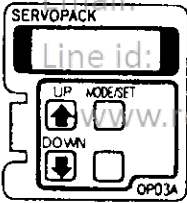

Use the table below to select Mating Connectors for your SGMS Sigma Servomotor.

Connector Description (D)	Motor Size (kW)	Part Number		Comments	Item Class
		without Brake	with Brake		
MS Connector for Motor Power Cable *	 1.0, 1.5, 2.0	MS3106B18-10S	MS3106B20-15S	Straight-type connector L-type connector Cable clamp	Stock
		MS3108B18-10S MS3057-10A	MS3108B20-15S MS3057-12A		
	3.0, 4.0, 5.0	MS3106B22-22S	MS3106B24-10S	Straight-type connector L-type connector Cable clamp	
		MS3108B22-22S MS3057-12A	MS3108B24-10S MS3057-16A		
MS Connector for Encoder Cable (incremental or absolute encoder)		MS3106B20-29S MS3108B20-29S MS3057-12A		Straight-type connector L-type connector Cable clamp	
1CN Mating Connector		DE9406970 DE9406970		Can use 1CN for analog speed and torque monitor service checks.	
2CN Encoder Mating Connector		All www.repairtw.com DE9406973		-	
3CN Peripheral Mating Connector		Stock 9-pin male D-shell connector		Source locally.	-
5CN Connector and 1m Cable with Pigtails		DE9404559		-	Stock

\* Choose either a straight or L-type connector and the associated cable clamp for a complete assembly. For example, L-type connector MS3108B18-10S is compatible with cable clamp MS3057-10A.

## Peripheral Device Selection

Use the table below to select Peripheral Devices for your SGMS Sigma Servomotor.

Component (E)	Image	Part Number	Description	Item Class
Hand-held Digital Operator Panel		JUSP-OP02A-1	Portable unit with built-in cable	Stock
Digital Operator Panel		JUSP-OP03A	Plugs into front of amplifier	Non-Stock
SVMON Software		SVMON	Programming software for DOS 3.3 on a 3.5" floppy disk	Stock
Software Interface Cable		YS-11	Pre-wired 1.5 meter cable with 9-pin connector	

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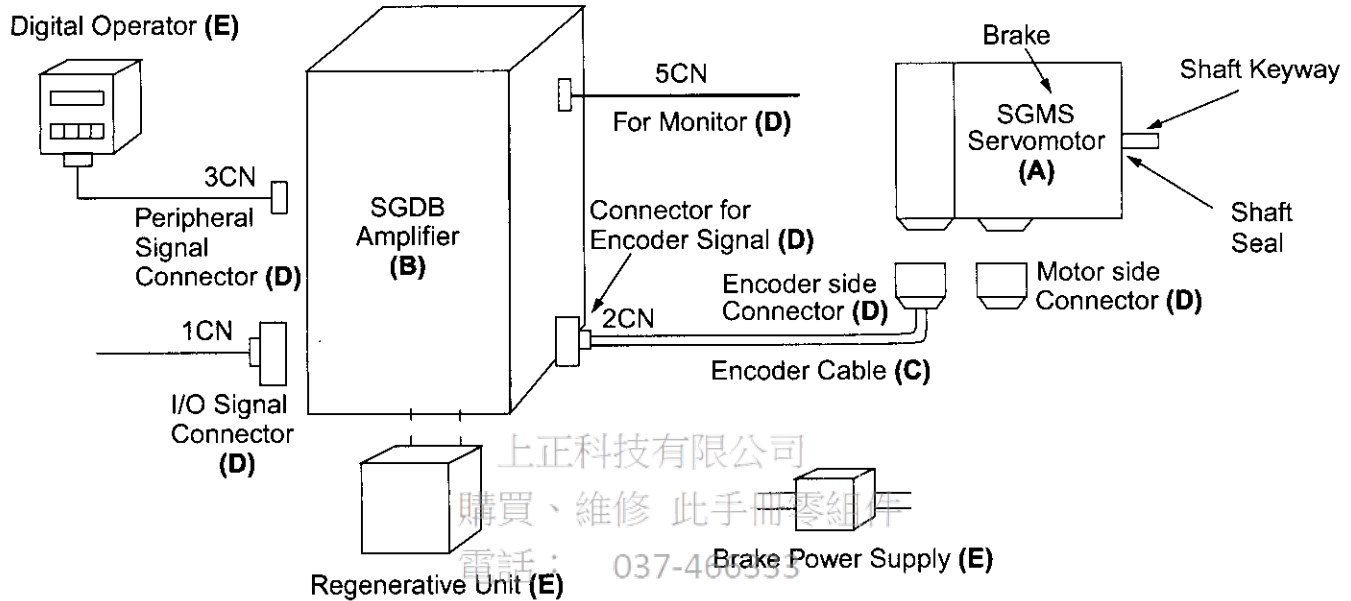
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# Selecting Your SGMS Sigma Servo System

Use the diagram below to locate and identify the components of your system. Each item is letter-coded and cross-referenced in the option tables on the following pages.

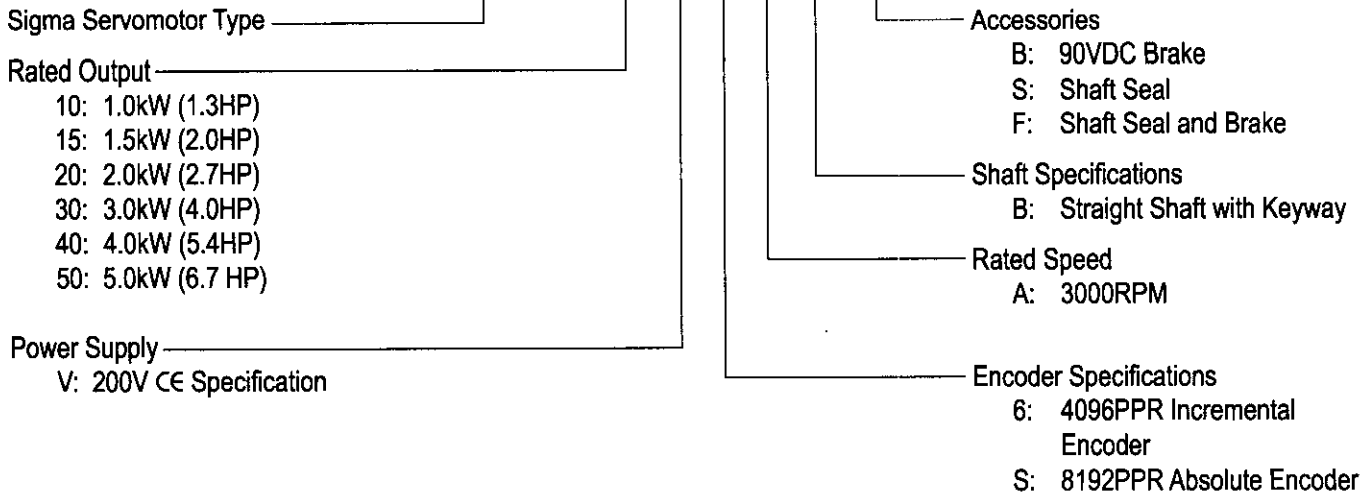
## System Configuration



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## Model Number Designation

### SGMS - 10 V 6 A B B



## Servomotor & Amplifier Selection

Use the table below to select the appropriate SGMS Sigma Servomotor and Amplifier.

Description	Peak Torque (in. lb.)	Rated Torque (in. lb.)	Motor Inertia (in. lb. sec <sup>2</sup> × 10 <sup>-3</sup> )	Motor MODEL # (A)	Amplifier MODEL # (B)* Analog/Digital Input SGDB-	Motor Item Class
200V 3-Phase  4096 PPR Incremental Encoder  Straight Shaft with Keyway  MS Connectors	84.4	28.2	1.54	SGMS-10V6AB	10VD (Limited Stock)	Limited Stock
				SGMS-10V6ABB		Non-Stock
	130	43	2.19	SGMS-15V6AB	15VD (Limited Stock)	Limited Stock
				SGMS-15V6ABB		Non-Stock
	169	56.4	2.82	SGMS-20V6AB	20VD (Limited Stock)	Limited Stock
				SGMS-20V6ABB		Non-Stock
	260	87	6.2	SGMS-30V6AB	30VD (Limited Stock)	Limited Stock
				SGMS-30V6ABB		Non-Stock
	336	112	8.5	SGMS-40V6AB	60VDY6 (Limited Stock)	Limited Stock
				SGMS-40V6ABB		Non-Stock
	422	140	11	SGMS-50V6AB	60VDY7 (Limited Stock)	Limited Stock
				SGMS-50V6ABB		Non-Stock

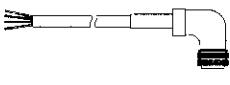
Note: 90VDC brakes for SGMS Sigma servomotors (CE) are standard. See Peripheral Device Selection in this section to order a power supply.  
For technical information, request technical document numbers PI-6021 and DE9409784 from your Yaskawa representative.

\* For more detailed SGDB amplifier specifications and dimensions, refer to page 127.



Pre-wired Cable Selection

Use the table below to select Pre-wired Cables for your SGMS Sigma Servomotor.

Cable Description (C)	Motor Size (kW)	Part Number:		Comments	Item Class
		without Brake	with Brake		
Power Cable with Connectors 	1.0, 1.5, 2.0	B1CE-□	B1BCE-□	Use the following key to specify required cable length (last digit of part #): 1: 3 meters 2: 5 meters 3: 10 meters (standard) 4: 15 meters 5: 20 meters	Limited Stock
	3.0	B2CE-□	B2BCE-□		
	4.0, 5.0	B3CE-□	B3BCE-□		
Encoder Cable (incremental or absolute)		A1CE-□			Limited Stock
Encoder Cable Only for Solder Connections		DP8409123		Up to 70 feet; for use with mating connector.	Stock *
Encoder Cable Only for Solder Connections		DP8409179		Over 70 feet; splice cable to accommodate connector.	
Encoder Cable Only for Solder Connections		All			
Input/Output 1CN Cable & Transition Terminal Block		JUSP-TA50P		35 mm din rail mountable; the cable length is 0.5 meters.	Stock *
Input/Output 1CN Cable with Pigtail Leads		DE9406969-□		Use the following key to specify required cable length (last digit of part #): 1: 1 meter (standard) 2: 2 meters 3: 3 meters	

\* Standard cable lengths are Stock items; non-standard cable lengths are Limited Stock items.



## Mating Connector Selection

Use the table below to select Mating Connectors for your SGMS Sigma Servomotor.

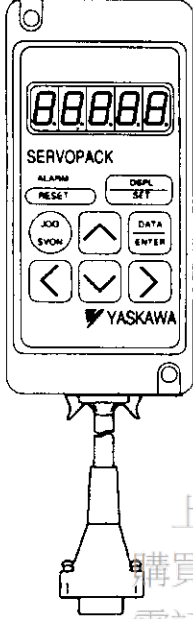
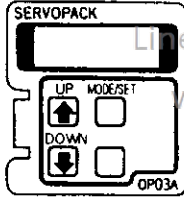

Connector Description (D)	Motor Size (kW)	Part Number		Comments	Item Class
		without Brake	with Brake		
Connector for Motor Power Cable *	1.0, 1.5, 2.0	JL04V-8A18-10SE-EB JL04-18CK(13)	JL04V-8A20-15SE-EB JL04-2022CK(14)	L-type connector Cable clamp	Limited Stock
	3.0, 4.0, 5.0	JL04V-8A22-22SE-EB JL04-2022CK(14)	JL04V-8A24-10SE-EB JL04-2428CK(17)	L-type connector Cable clamp	
Connector for Encoder Cable (incremental or absolute encoder)		JA08A-20-29S-J1-EB JL04-2022CKE(12)		L-type connector Cable clamp	
1CN Mating Connector		上正科技有限公司 購買、維修 此手冊零組件 電話：037-466333 Email: service@repairtw.com Line id: @zzzz		Can use 1CN for analog speed and torque monitor service checks.	
2CN Encoder Mating Connector		All www.repairtw.com		-	
3CN Peripheral Mating Connector		Stock 9-pin male D-shell connector		Source locally.	
5CN Connector and 1m Cable with Pigtails		DE9404559		-	Limited Stock

\* Choose the connector and the associated cable clamp for a complete assembly.



Peripheral Device Selection

Use the table below to select Peripheral Devices for your SGMS Sigma Servomotor.

Component (E)	Part Number	Description	Item Class
<p>Hand-held Digital Operator Panel</p>		<p>JUSP-OP02A-1</p>	<p>Portable unit with built-in cable</p> <p>Stock</p>
<p>Digital Operator Panel</p>		<p>JUSP-OP03A</p>	<p>Plugs into front of amplifier</p> <p>Non-Stock</p>
<p>SVMON Software</p>		<p>SVMON</p>	<p>Programming software for DOS 3.3 on a 3.5" floppy disk</p> <p>Stock</p>
<p>Software Interface Cable</p>		<p>YS-11</p>	<p>Pre-wired 1.5 meter cable with 9-pin connector</p>

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## NOTES

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